OPERATION MANUAL

(Including Guidelines for Safe Operation)

HE-2910



INTRODUCTION

Thank you very much for purchasing our product.

- Please be sure to read this manual carefully and understand the contents before the actual operation in order to keep your safety.
- ■Please store this manual safely at the convenient place so that you can read it when needed.
- ■Please pass this manual to new owner when you resell or give this unit to someone else.
- •We are not responsible for any physical injuries and property damages under product liability (PL) law by wrong usage or any other operations not described in this manual.



Do not reproduce a part or all of contents described in this manual.
Please understand that the unit may differ from the contents described in this manual due to the specification changes

- etc.
- Please inform us if you see any errors and/or unclear descriptions in this manual.

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CAUTION ON SAFETY (BE SURE TO READ THIS)

This explains the important cautions in order to prevent the users and surrounding people from physical injuries and property damages.

1. HANDLING OF MAIN UNIT



ACAUTION

•Do NOT install the unit where rain or spray dashes hit directly. It causes the firing and electric shock.



•Do NOT install the unit at heated places. It causes the firing from the increase of internal temperature, injury, and electric shock.

•Use the earthing. Noise influence can be prevented by firm earthing.

 Away from direct sun light. It causes the difficulty of future vision and heat problem.

2. HANDLING OF CABLE

WARNING

•Be sure to use the specified power supply cable. It causes firing and heating.





•Be sure to wire the cables for safety pilot. The improper wiring causes the accident. *Do NOT put the heavy object on cables or bend cables excessively.

•Do NOT disassemble or modify the cables. It causes firing, heating, or electronic shock.

•Do NOT use damaged cables. It causes firing or electric shock.

A CAUTION

•Do NOT pull out the cable when disconnecting the plug. The cable damage causes firing and electric shock. *Be sure to hold and pull the plug itself for the removal.

• Do NOT put any pressure on cables when installing the unit. It causes line cut and shortage.

3. HANDLING TRANSDUCER AND WATER TEMP SENSOR



It causes electronic shock.

4. REMOTE

•Do NOT use any leaked AA-batteries. (for IR usage) It may cause human injuries if a person touches the leaked liquid.

•Place the remote for safe location when not being used. Prevent from dropping and human accident.

5. HANDLING OF GPS

•Do NOT work on GPS while piloting. The work such as installation or maintenance should be carried out on ground.

•Place GPS antenna at highest location as possible for stable GPS signal.

Searching time for GPS signals take longer, and GPS accuracy becomes lower if any obstacles are located near by GPS antenna.

6. OPERATION

Power OFF when starting engine.

Battery voltage varies when the engine starts. It may cause some damages onto the unit. Set the power OFF when starting the engine.

Power Supply 11-30V

Operate the unit within the range of DC11-30V.

Organic solution is prohibited.

Do NOT clean the unit with organic solution like thinner or alcohol etc because most parts are made with plastic. For heavy dirt, soak cloth in synthetic detergent and clean it after wring.

Take note of important data

The unit is not designed for storing the data permanently. Important data should be recorded on the notebook etc.

Approx.±5m is considered for GPS variation normally under good conditions.

However, this may shift to appox.±10-30m under unfavorable conditions.

8. CHIRP TECHNOLOGY

Echo presentation of chirp echo sounder appears differently compared to conventional sounder.

With sweeping range of multiple frequencies, Hondex chirp sounder can utilize more information and achieve higher resolution of screen image such as target fish and sea bottom compared to conventional sounder.

The chirp transducer must be "Thru-Hull" installation.

MEMO

DESCRIPTIONS

1.FRONT PANEL



- ① Frequency1
- 2 Frequency2
- 3 Zoom
- ④ Clutter
- (5) Setup short-cut key
- 6 User key

- ⑦ Menu
- ^⑧ Set
- (9) Direction key
- 10 Clear
- 1 Mode display switch
- 12 Depth
- 13 Shift
- (14) Gain1 (sensitivity)
- (15) Gain2 (sensitivity)
- 16 Power On/Off
 - Brightness adjustment
- 1 Card slot for SD and USB device

2. REAR VIEW



①DVI monitor output
②Water temp sensor (TEMP, 8P)
③External input/output (NMEA1, 6P)
④Remote (4P)
⑤External input/output (NMEA2, 6P)
⑥GPS (GPS, 6P)
⑦Transducer (5P)
⑧DC Power (2P)
⑨Earth Terminal

MEMO

HOW TO SEE THE DISPLAY



Water temp sensor : Option



HOW TO OPERATE MENU



BASIC OPERATION

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POWER ON/OFF



INITIAL SET-UP (TD LOCATION SET-UP)

The following display appears after 1st time power on. Select the proper one.

Select the location of transducer installed. Use ▲ or ▼ to change the set-up. Press "MENU" after completing the set-up. Not selected IN-HULL (Select this when using In-Hull or Inside-Case installation.) THRU-HULL (Select this when using thru-hull installation.)

Also, this TD set-up can be changed from menu. (Refer to "TRANSDUCER THRU-HULL / IN-HULL SET-UP" p52.)

SCREEN BRIGHTNESS



SIMULATION MODE

SIMULATION

Go to 8.OTHERS – 6.OTHER – 5.INITIAL – 2.SIMULATION. Use Direction key to select the different demo mode.

OFF : No simulation mode

ON : Simulation mode

DEMO icon appears when activating simulation mode.
 Select OFF and press SET key to return to the normal mode.
 Caution) Simulation mode is only for practice or exhibition usage.
 Information shown on DEMO screen is not actual info such as depth etc.

NMEA0183 OUTPUT

On/Off NMEA Output

Go to 8.0THER – 6.0THER – 4.EXT TERMINAL – 3.NMEA1 OUTPUT or 4.NMEA2 OUTPUT.

ON : Output

OFF : No output

NMEA0183 Output Interval

Go to 8.0THER – 6.0THER – 4.EXT TERMINAL – 1.INTERVAL SETUP1 or 2.INTERVAL SETUP2.

2 Each interval can be selected.

%Interval set-up may be disabled when outputting too much data.
%Please refer to p.48 for NMEA0183 output sentence.

BAUD RATE Set-up for NMEA0183 and GPS

Go to 8.0THER – 6.0THER – 4.EXT TERMINAL – 5.NMEA1 PORT BAUD RATE, 6.NMEA2 PORT BAUD RATE.

%GP-16H: 4800, GP-17H(HD): 9600 %Reboot the unit after change of this set-up.

SCREEN CAPTURE TO USB DEVICE

Possible to save the screen image to USB device. PNG format 800x600



INITIALIZE

Go to 8.OTHER - 6.OTHER - 5.INITIAL – 1.INITIAL ALL

2 Press SET key to execute the initialization.

INITIAL ALL : Return to factory set-up. Required to reboot the unit. %Any erased data cannot be regenerated.

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SOUNDER SCREEN





%1 Water temperature

Optional water temp sensor is required to show water temp.

%2 GPS Info

EXT appears when using an external GPS.

DEPTH SET-UP



WIDEBAND SET-UP

Wideband Frequency

1

Press the set key to select the target pane. A red frame is drawn on the selected screen frequency.

2 Press FREQ \blacktriangle key for change frequency.

SENSITIVITY

Whole Display Gain Adjustment

Digital echo sounder is capable of changing the whole past image. This function helps to find the optimized gain set-up for whole image (past recording data) with easy manual operation.



Dual Frequency Display

For dual frequency display, GAIN1 is for right display, and GAIN2 is for left display.



EXPANSION MODE

Expansion Mode [Expansion Display] Expanded display appears on the left side. When selecting dual frequency mode, the right-side frequency is applied for expanded display. Press 4.EXPANSION – 1.EXP MODE. **2** OFF : Normal display appears. BOTTOM LOCK : Straight bottom contour and expanded area from the bottom. Auto Zoom : Set the bottom at center position and expand upper/lower area. Manual Zoom : Set the selected location at center and expand upper/lower area. Use Zoom key to move the expansion area. *Display range varies depending on the expansion ratio.

EXPANSION AREA



WATER TEMP ALARM



FISH ALARM



DEPTH ALARM



WATER TEMP CORRECTION



FREQUENCY DISPLAY

Frequency Display

Possible to select dual frequency display as follows.



Go to 1.DISPLAY.

2 Select both(low/high) frequencies on the screen.

<In case of "50-200">

When using Auto-Gain (→page28), right display is only applied for Auto-Gain function.

SWEEP SPEED

Sweep Speed

[Sweeping Speed]

Sounder display consists of the consecutive latest image (image beneath the vessel) at the right edge and keep shifting the past image to the left side. Sweeping speed is the speed to shift the image. Whole screen appears differently with this set-up value.

[Relation between Sweeping Speed and Sounding Rate]

Sweeping speed can be selected from 8 different types. The following is the reference of sounding rate for each set-up.

Menu Set-up	Sweep Speed / Sounding Rate	1	Go to 2.SWEEP SPEED.
× 3	3⁄1	🛦 Fast	
× 2	2⁄1	2	Select one.
4	1/1		MENUL varies depending on each mode
3	1⁄2		
2	1⁄4	Slow 🕈	
1	1⁄8		• CHIRP : OFF, 1, 2, 3, 4
Freeze	Freeze		• FISH SYMBOL(ON) : OFF, 4
			• TRADITIOAL : OFF, 1, 2, 3, 4, S, $\times 2$, $\times 3$

SOUNDER SET-UP

Select AUTO or MANUAL set-up for the depth (range) & sensitivity (gain).

Go to 3.AUTO MODE.

2 AUTO enables the selected AUTO functions in the following detailed set-up.

AUTO or MANU indicator appears above gain bar.

DETAIL SET-UP



A MODE



BACKGROUND COLOR



COLOR CONFIGURATION

Color Configuration

Reflected signal of sound wave is converted into 17 ranks of digital signal

according to the strength of response. Color configuration is the color $% \left({{{\left[{{C_{{\rm{c}}}} \right]}}} \right)$

set-up for 16 ranks except background color.

Sounder image is shown by the color configuration. The displayed color shows the strength of reaction. Also, specific reaction can be emphasized by changing the color configuration.

Go to 6.COLOR SETUP – 2.COLOR CONFIG.



COLOR ERASE

Color Erase

Set-up the erase level so that fish schools can be seen clearly.

Go to 6.COLOR SETUP - 3.COLOR ERASE.

2 Select one.

INTENSE LEVEL

Intense Level

This set-up shows more color of strong reflection (signal).



Go to 6.COLOR SETUP - 4.INTENSE COL.

2 Select one.

STD ΗT MAX 🕈

CLUTTER

Clutter

Fish school and bottom are displayed with the set-up of reflected echo strength and color tone. "Clutter" easily distinguishes the fish school by erasing the color from weakest reflection such as plankton or dirt under the water.

Go to 6.COLOR SETUP - 5.CLUTTER.

STD 2

1 2 3 Less noise toward higher number.

DEPTH UNIT Depth Unit Select from "meter", "feet", "fathom", or "Brazas". 1 Go to 8.0THER - 1.DEPTH UNIT. 2 Select one.



SUPER RANGE	
Super Range	
Whole past image changes auto (displayed depth range on scree	omatically according to the current depth en) if changed any.
1	Go to 7.DISPLAY SETUP – 3.SUPER RANGE.

WATER TEMP GRAPH

			<u>۱</u>
Water	Temp	Graph	. Г
vvacci	remp	Grupn	

Water temp graph appears. Easy to see the fishing points by knowing the variation of water temp and tide change.

Go to 7.DISPLAY SETUP – 4.TEMP GRAPH.

*Optional water temp sensor is required to show the graph.

AUTO RANGE MAX. DEPTH



CLEAN ECHO



STC

STC Setup

Reduce the sensitivity of shallow water area by eliminating the noise signals such as plankton and air bubbles.

Go to 8.0THER – 2.SPECIAL SETUP – 3.STC SETUP.

2 Set-up STC



{Low-Freq STC Level> (High-Freq STC Level>
 Set-up STC level for either low-freq or
 high-freq.
 Low sensitivity at shallow area with

stronger STC.

4 different STC level: OFF, Low, Mid, High OFF: Weakest, H: Strongest



〈Low-Freq STC Depth〉〈High-Freq STC Depth〉 Set-up the target depth for STC adjustment (low-freq or high-freq) Deeper the depth is selected, selected STC level is affected to deeper water. 3 different STC target depth: Shallow, h Normal, Deep. Shallow: 0~50m, Normal: 0~150m, Deep: 0~300m

OUTPUT POWER



PULSE LENGTH



SENSITIVITY MODE



SOUNDER DISTANCE SCALE

Distance scale displayed on the sounder screen. To give you an idea of how far away the target is located from an own vessel. **1** Go to 7.DISPLAY SETUP – 5.DIST SCALE. **2** OFF : No show TOP : Scale display on the top BOTTOM : Scale display at the bottom **Distance scale number does not appear until echo image reaches to the left edge screen. **No distance scale number when the distance is 20m or less.

BOTTOM HARDNESS FUNCTION

Bottom Hardness Function	ı	
Bottom Hardness Level Hard Bottom Soft Bottom The value appears on the up Also, bottom hardness graph	: 0~20 : Higher value : Lower value per left of screen. appears at the botto	m.
Go to 7.DISPLAY SETUP - HARDNESS SETTING - HARDNESS GRAPH.	- 6.BOTTOM 4.BOTTOM	
Note) Applicable for shallow w The value varies depend conditions of transducer	vater. ling on the · installation etc.	Bottom Hardness

PRESET FUNCTION

PRESET FUNCTION

Each set-up parameter can be saved and recall by short-cut keys of A/B/C.

Press&hold A, B or C button to save the selected parameter.



TRANSDUCER THRU-HULL / IN-HULL SET-UP

TD Location

Go to 8.OTHER - 2.SPECIAL SETUP - 8.TD LOCATION.

2 Select one.

THRU-HULL-A	:Custom. Not to be used normally.
THRU-HULL-B	:Normal. Select this when using thru-hull installation.
IN-HULL-A	:Select this when using in-hull or inside-case installation.
IN-HULL-B	:Custom. Only for the case IN-HULL-A is not working properly.

BROADBAND FREQUENCY TUNING

Frequency Tuning

Go to 9.WIDEBAND

CHIRP : n/a

TRADITIONAL w/ wideband transducer : Choose Freq to use.

SET-L : Low Freq

SET-H : High Freq

TRADITIONAL w/ conventional transducer : n/a

LIST OF ECHO SOUNDER MENU

Menu Item

% Factory set-up

1. DISPLAY	(→page19,27)		CHIRP L-H, CHIRP L-L, CHIRP H-H,	
			CHIRP L, CHIRP H, CHIRP H-L	
			In case of ID361.	
2. SWLLF SFL	_D(→pagez7)		%S.x2.x3 not available for CHIRP TD	
3. AUTO MODE	(→page28)		MANUAL , AUTO	
4. EXPANSION	1. EXP. MODE	(→page23)	OFF , BOTTOM , AUTO ZOOM , MANUAL ZOOM	
	2. EXP. RATE		x2 , x4 , x8	
5. FISH	1.FISH SYMBOL		OFF,ON,ON(SIZE)	
SYMBOL	2.FISH DEPTH		OFF, FROM SURFACE, FROM BOTTOM	
%NOT FOR	3.SYMBOL TYPE		FISH, STREAMER, FRAME	
CHIRP TD	4. SYMBOL CALIB			
6. COLOR	1. BACKGROUND	(→page29)	BLACK , BLUE , WHITE , D.BLUE	
SETUP	2. COLOR CONFIG	(→page30)	4 (0~7)	
	3. COLOR ERASE	(→page30)	OFF (OFF~12)	
	4. INTENSE COL	(→page31)	STD , HI , MAX	
	5. CLUTTER	(→page31)	STD , 1 , 2 , 3	
7. DISPLAY	1. A-MODE	(→page29)	OFF , ON	
SETUP	2. SCALE LINE	(→page32)	OFF , ON	
	3. SUPER RANGE	(→page32)	OFF , ON	
	4. TEMP GRAPH	(→page33)	OFF , ON	
	5. DIST SCALE	(→page38)	OFF , TOP , BOTTOM	
	6. BTM HRADNESS SETTING	S1.BTM HARDNESS OFFSET	0 (-2~2)	
	(→page39)	2.BTM HARDNESS AVE	1,2,3	
		3.BTM HARDNESS SENS	SH, • , • , • , • , L	
		4.BOTTOM HARDNESS GRAPH	OFF , ON	
8. OTHER	1. DEPTH UNIT	(→page32)	m , ft, fa , br	
	2. SPECIAL SETUP	1. AUTO RANGE MAX	30m, 50m, 100m, 300m, 500m, 1000m	
		$(\rightarrow page33)$		
		$(\rightarrow page 33)$	OT , ⊑, M, H	
		3. STC SETUP(\rightarrow page34	4)	
		1. STC (LOW FREQ)) OFF , L , <mark>M</mark> , H	
		2. STC (HIGH FRE	Q) OFF , L , M , H	
		3. STC DEPTH (LO	W FREQ) SHALLOW , NORMAL , DEEP	
		4. STC DEPTH (LO	W FREQ) SHALLOW , NORMAL , DEEP	
		4. OUTPUT POWER	OFF , LOW , <u>HIGH</u>	
		(→pagess)	S CTD I	
		$(\rightarrow nage 36)$	3, <mark>310</mark> , L	
		6. SENSITIVITY	STD , HIGH	
		(→page37)		

		7. AUTO MODE SETUP			
		1. A	AUTO GAIN	OFF , LOW ,	HIGH
		2. A	AUTO RANGE	OFF , RANG	, SHIFT
		8. TD LC	CATION 1	IN-HULL-A,	IN-HULL-B,
		(→page4		THRU-HULL-	A, THRU-HULL-B
		9. UITE	R SPECIAL SETU	P	
		1. FINDEER DETAIL SETUP 1			
			1. L FREQ. MIN	DEPTH LV	0dB (-20~+12db)
			2. H FREQ. MIN	I DEPTH LV	0dB (-20~+12db)
			3. L FREQ. MIN	DEPTH	0.37 m (0.25~6.11m)
			4. H FREQ. MIN	I DEPTH	0.37 m (0.25~6.11m)
		5. L FREQ. AUTO GAIN ±0 (-5~+5)			
			6. H FREQ. AUT	O GAIN	±0 (-5~+5)
			CORRECT.		
		2. F	INDER DETAIL S	SETUP 2	
			1. BANDWIDTH		WIDE , STD , NAR-1 , NAR-2
			2. TARGET DEP	TH RANGE	X1 , x2 , AUTO
			3. DEPTH MEAS	5	AUTO, RIGHT-DISP
	3.EXT SYNC		OFF, ON		
	4.HEAVE ADJUST		OFF, ON		
	5.ALARM	1. TEMP	ALARM		
		2. FISH ALARM			
		3. DEPTH	H ALARM		
	6.OTHER	1. MEMO	RY CARD		
		2. UNIT	SWITCH		
		3. CORR	ECTION		
		4. EXT T	ERMINAL		
		5. INITIA	AL.		
9.WIDEBAND	1. MODE		TRADITIONAL,	CHIRP	
	2. SET-L		38kHz,40kHz,4	5kHz, <mark>50kHz</mark>	,
	3 SET_H		33KHZ,0UKHZ,0	ンドロイン/UKHZ	
	J. JLI-11	130KHZ,140KHZ,130KHZ, 160kHz 170kHz 180kHz			
			190kHz,200kHz	,210kHz,	
			220kHz		

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DIMENSIONAL DRAWING

1.MAIN UNIT

Unit : mm



2.BRACKET

Unit : mm



CONNECTION WITH MAIN UNIT



CONNECTOR DIAGRAM

Caution: Connectors on display unit.



Connector for Power Supply
 Power Supply (+) 11~30V
 Power Supply (-)



- 2. Connector 5P for Transducer
 - 1. freq A(+) / CHIRP-L
 - 2. freq B(+) / CHIRP-H
 - 3. Shield
 - 4. freq B(-) / CHIRP-H
 - 5. freq B(-) / CHIRP-L

(Example) TD Line Info(TD361)

5P Spec	1	-(Black) CHIRP-L
	2	-(Green)CHIRP-H
	3	Shield
	4	+(Red) CHIRP-H
	5	+(White) CHIRP-L



- 3. Connector for Water Temp
- Sensor
 - 1. N/A
 - 2. N/A
 - 3. N/A 4. N/A
 - 5. N/A
 - 6. Water Temp Sensor(+)
 - 7. Water Temp Sensor(-)
 - 8. N/A

- 4. Connector for External Input/Output
 - 1. GND
 - 2. Data Input(-)
 - 3. Data Input(+)
- 4. N/A
- 5. Data Output
- 6. DC10.5V (200mA)Output

GPS ANTENNA MADE BY OTHER COMPANY

% The performance&accuracy is not covered by the warranty when using GPS antenna of different brand.

NMEA CONNECTOR

Input/Output Connector

To be used when connecting to other device.



NMEA0183 OUTPUT SENTENCE

The following sentence is output.

The output interval can be set from OFF, 1sec, 2sec, 4sec.

%GGA,GLL,VTG,RMC: Available only when receiving the data from GPS receiver. %Same output interval is used for HDG and HDT.

%The output interval might be longer when selecting many items.

☆Factory set-up

1sec: DBT, MTW OFF: Other items

Example for output sentence

\$GPGGA,110147,3443.160,N,13726.746,E,1,09,001,00070,M,0025,M,,*55 \$GPGLL,3443.16,N,137.26,E*55 \$GPVTG,118.9,T,,,000.0,N,000.0,K*2C \$GPRMC,110146,A,3443.160,N,13726.746,E,000.0,118.5,270707,,*15 \$GPAPB,A,A,00.001,R,N,V,V,001.4,T,000,001.4,T,,*77 \$HCHDG,000.0,,,,*5C \$GPXTE,A,A,00.001,R,N*71 \$GPBOD,001.4,T,,000,1000*10 \$GPBWC,110100,3508.785,N,13727.496,E,001.4,T,,025.63,N,000*69 \$SDDBT,209.6,f,63.9,M,34.9,F*28 \$SDMTW,27.6,C*1A

MAIN UNIT INSTALLATION

AWARNING

•Install the unit firmly.

If not, it may cause the human injuries.

*Install the unit correctly according to the following instruction.

•Do NOT install the unit where rain or spray dashes hit directly. It causes the firing and electric shock.

[Procedure of Installation]

<Installation of Main Unit>

Fix the unit with enclosed screws by using bracket holes (4 locations). Refer to the picture below.

Please fix main unit with four mash-room head tapping screws 5x20.



BUILT-IN INSTALLATION

WARNING

•Install the unit firmly.

If not, it may cause the human injuries.

*Be sure to follow the instruction below and official installation method.

Fix the unit by using 4 holes on the front panel.



1. Refer to the following figure for fixation holes.



- 2. Raise 2pcs side covers.
- 3. Remove the covers.





4. Flash-mount it.



5. Fix with 4pcs 4×30 screws.



6. Put the side covers back.



TRANSDUCER INSTALLATION

•Any works on the vessel are very unstable and risky.

Installation/maintenance of transducer should be handled after landing the vessel on ground or fixing the vessel at shipyard etc.

If not, it may cause serious injuries.

WARNING



•Be sure to ventilate well inside the vessel when installing the transducer at the bottom of vessel.

Volatile gas from solvent etc causes the toxic symptoms.



•Water proof treatment is required for Thru-Hull installation. If not, it causes the marine accident.

•Do not operate the electronic tools with wet hands. It causes electronic shock.



•Thru-Hull installation is required for Chirp/Wideband transducers. If not, it causes the damage onto transducers.

[Installation Method]

The following installations can be applied for conventional transducers.

Please refer to each instruction.

- 1. Inside-Hull
- 2. Thru-Hull

%These methods prohibit the use of aluminum vessels for the risk of corrosion. %Be careful about the following points when using the method 1.



1. INSIDE-HULL

※Effective for FRP vessels with single hull layer of 10mm or less.※Size and shape vary for each transducer.

Look for the best picture location before the fixation by putting adequate water on the transducer surface and vessel bottom followed by pressing the transducer onto the vessel bottom.

- Polish the adhesive surface (transducer bottom surface and vessel bottom) well with sandpaper (#240 or around) and alcohol in order to remove oil, water, and dirt on the surface.
- (2) Put silicon bond on the adhesive surface (transducer bottom surface and vessel bottom) and press firmly for the bonding so that no air bubble is contained inside.



2. THRU-HULL

- (1) Make hole of ϕ 25 at the vessel bottom. (Aluminum vessels are not subject to the installation for the risk of corrosion.)
- (2) Insert the screw part of transducer into the hole and fix it with 1pc cork washer, 1pc washer, and 1pc nut. (Extra cork washer is for spare.)

%Execute the waterproof care for the junction part.

For tilted hull, use a block etc to face directly to the vessel bottom. %Size and shape vary for each transducer.



Keep the inclination of transducer surface below 10° or less.



Put the seal at joint point for waterproof.

WATER TEMP. SENSOR INSTALLATION

*Water temp sensor: Option

•Any works on the vessel are very unstable and risky. Installation/maintenance of water temp sensor should be handled after landing the vessel on ground or fixing the vessel at shipyard etc. If not, it may cause serious injuries.

•Do not operate the electronic tools with wet hands. It causes electronic shock.

[Installation of Thru-Hull Water Temp Sensor (15m)]

℁For FRP vessel only.

(The use of this sensor is prohibited for aluminum vessels due to the risk of corrosion.)



[Installation of Transom Water Temp Sensor]



STANDARD CONFIGURATION



OPTIONS



THEORY OF ECHO SOUNDER

1. Theory of Echo Sounder

•Theory of echo sounder is same as echo among hills. Ultrasonic wave transmitted from the transducer directly beneath the vessel is reflected at the sea bottom and received by transducer.

Echo sounder indicates the depth by calculating the round-trip time to distance. Also, the unit shows the color image of fish school size/density or sea floor condition according to the strength of reflected wave.

Ultrasonic wave runs at 1500m/sec inside the water. Therefore, the depth to fish school and sea bottom can be captured by calculating the round-trip time.



•Display Method

Current image is shown at 1st line of right edge after processing the reflected wave of transmitted ultrasonic. The line image previously located at the right edge moves to one line to the left.

Keep executing this operation to create the cross section view.

Therefore, the latest image beneath the vessel is located at the right edge. More left side the image moves, more past image the screen shows.

You can assume that echo sounder screen shows the image from the side view. The sea floor shape can be only captured when sailing the vessel. No matter how the bottom is shaped, the image shows the flat bottom if the vessel is stopped. $\leftarrow Past Image$



Caution : There is no relationship between vessel speed and image line speed.

2. Distinguish of Fish School

•Important tip is comparison between fish school image and actual fish. Possible to judge the fish type to some extent from the image of fish school. The shape of fish school changes even for same fish group by time (day/night, season, current change).

The important tip is to distinguish the fish type image and actual catch and look for the point.

3. Distinguish of Fish Quantity

•Distinguish fish quantity from density/size of fish school.

Higher density of fish school has stronger reflected wave. Therefore, the fish density can be seen from the color strength of image.

It is wrong that fish quantity is large for large image on the screen. Fish school located deeper area tends to appear bigger compared to the one at shallow water. This is because the width of transmitted wave becomes wider as it go deeper. The reflected ultrasonic wave becomes bigger as the distance (depth) gets further. The important tip to distinguish the fish quantity is to know fish school located at deeper water appears bigger.

Judge from size of fish school and color strength.



4. Distinguish of Sea Floor Condition – ●There are many types of sea floor conditions such as rocky, sandy, or muddy.

The condition can be judged by the upper/lower width of sea floor image and 2nd echo. The reflection is stronger for hard bottom such as rocky area. The image width is thicker, and 2nd echo tends to appear.

On the other hand, the reflection is weaker for soft bottom such as sandy and muddy area. The image width is thinner, and it's harder to have 2nd echo. <Rocky Area>



<Sandy or Muddy Area>



TROUBLE SHOOTING

•When the unit has any problems, please check the following points before returning the unit for repair.

Symptom	Cause	Remedy
Power cannot be	Voltage of battery is lower	Recharge the battery.
turned ON.	than standard value (11V).	
	Contact of power connector is	Retighten it. Remove and clean
	poor.	the rust/dust. Replace it in the
		case of corrosion.
		\cdot Replace the power cable.
		\cdot Replace the connector on the
		unit.
	Wrong connection of power.	Check the polarity and connect it
	Opposite polarity +	properly.
	Cut the wire inside power	Exchange to new power cable.
	cable.	
	Blown fuse.	Send it for repair.
No display on	Brightness is set to minimum	Adjust the brightness. (Refer to
screen.	level.	[SCREEN BRIGHTNESS]
Latitude/longitude of own vessel are not	Data from satellite cannot be received well.	Check GPS antenna and cable.
indicated.	Data is not sent from GPS	Check setting of data output
	external GPS receiver)	(GGA) from GPS receiver.
	Numbers of received satellite	Wait for a while.
	is less (0~3)	(Approx. 5~30 minutes)
Display cannot be moved.	Cursor is shown on the screen.	Erase the cursor. (Refer to [CURSOR]
Just above on	Course-up function is set.	In case you want to set just
display and north of		above on display to north, set
map are swerved.		[DISPLAY DIRECTION]
Automatic Course	Setting method is wrong.	After setting Automatic Course
Up function is not available		Up function is set, press
		[DISPLAY DIRECTION]
Waypoint navigation	Latitude/longitude of own boat	Set after latitude/longitude are
cannot be set.	are not indicated.	indicated.
	Waypoint is not set.	Set the waypoint.(Refer to [ADVANCE WAYPOINT / RETURN
Route navigation	Latitude/longitude of own boat	Set after latitude/longitude are
cannot be set.	are not indicated.	indicated.
	Route is not set.	Set the route.
		(Refer to [SAVE (ERASE)
		ROUTE]

Symptom	Cause	Remedy			
Bottom or fish	Contact problem with transducer	Retighten the connection.			
cannot be displayed	connector.	Remove/clean the rust/dust.			
at all.		Replace it in the case of			
		corrosion.			
		• Exchange transducer.			
		 Send it for repair. 			
	<problem transducer="" with=""></problem>	•			
	Check followings and replace it in	the case of actual problems.			
	1. It's normal if you hear the se	ound like "Bo Bo" from the			
	surface of transducer.				
	2. It's normal if rain like dots appears on the transducer surface				
	after setting the sensitivity and depth to the max and rubbing				
	the transducer surface.				
	Transducer is not immersed	Adjust the transducer			
	enough into the water.	installation so that it is always			
		beneath water surface.			
	Internal liquid is not enough	Add enough liquid to immerse			
	inside the case.	the transducer.			
Image does not	Transducer is not immersed	Adjust the transducer			
appear sometimes.	enough into the water.	installation so that it is always			
		beneath water surface.			
	Problem with the transducer	Check the installation of			
	installation causes the image	transducer.			
	problem due to air bubbles at				
	speeding the vessel.				
	Influence from other vessel	Move to other location or wait			
	causing air bubbles.	until air bubble disappears.			
Bottom or fish	Too low sensitivity.	Increase the sensitivity.			
school is not		Or, set to auto gain (auto			
displayed well.		sensitivity control).			
	Rubbish and weed attached on	Remove the excrescence.			
	the transducer surface.	Remove the dirt from bottom			
	Dirty bottom or liquid.	and exchange the liquid.			
	Water and environmental conditions may cause the problem with				
	image which is not problem at all				
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	A REALEMENT AND				
	Too much sludge Lots of	Muddy and Papid current			
	weeds	dirty locations			
	Too high clutter.	Activate low reflection color.			
		Refer to [CLUTTER]			

Symptom	Cause	Remedy
Too much noise.	Too high sensitivity.	Lower the sensitivity.
		Set to auto gain (auto gain
		control)
	Interference with other	Noise disappears after other
	vessel's echo sounder.	vessel moves far away.
	Noise from engine.	Change the routing of cables
		such as transducer and power
		cables.
		(keep distance from the engine
		as far as possible.)

SPECIFICATIONS

Display	Display	12.1" TFT Color LCD		
	Display Style	Landscape		
	Number of Pixel	800 × 600		
	Operating Voltage	DC11V~30V		
	Dimension of Main	242(H)×358(W)×146(D)		
	Weight of Main Unit	Approx. 3.7kg		
	Frequency (kHz)	CHIRP 38-70kHz / 130-220kHz TRADITIONAL(depends on transducer)		
	Output Power (W)	1kW / 2kW / 3kW/ 5kW		
	Depth Range	0~2000m		
	Auto Range	OFF / Range / Shift		
	Auto Gain	OFF / Low / High		
	A-Mode	OFF / ON		
	Fish Alarm	OFF / S / L		
т	Water Temp Alarm	OFF / In Range / Out of Range		
cho	Depth Alarm	OFF / In Range / Out of Range		
Sor	Expansion Mode	OFF / Bottom Lock / Automatic Expansion / Manual		
Inde	Expansion Rate	x 2 / x 4 / x 8		
'n	Sweep Speed	8 levels (OFF , 1 , 2 , 3 , 4 , S , x2 , x3)		
	Background Color	4 Colors (Black, Blue, White, Dark Blue)		
	Color Configuration	8 Patterns		
	Depth Unit	Meter / Feet / Fathom / Brazas		
	Scale Line	OFF/ON		
	Super Range	OFF/ON		
	STC	OFF / L / M / H		
	Output Power	OFF / LOW / HIGH		
	Pulse Length	S / STD / L		



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